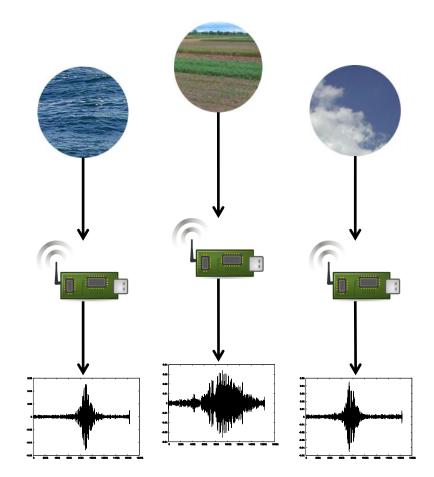
Markus Stocker Environmental Informatics Seminar, Kuopio, March 13, 2012

# Sensor networks: Too much data and not enough knowledge\*

Approaching the problem using ontology



### **Environmental monitoring and sensor networks**



- Environmental monitoring
  - "Observe and record the conditions of the natural environment" [1]
  - Involves *measurement* as the "process of empirical, objective, assignment of numbers to the properties of objects and events of the real world in such a way as to describe them" [2]
  - Sensor is a device that performs measurement over time
- Sensor layer
  - Physical layer, hardware
  - (Heterogeneous) sensor network
- Data layer
  - Raw spatiotemporal measurement data
  - Potentially high frequency

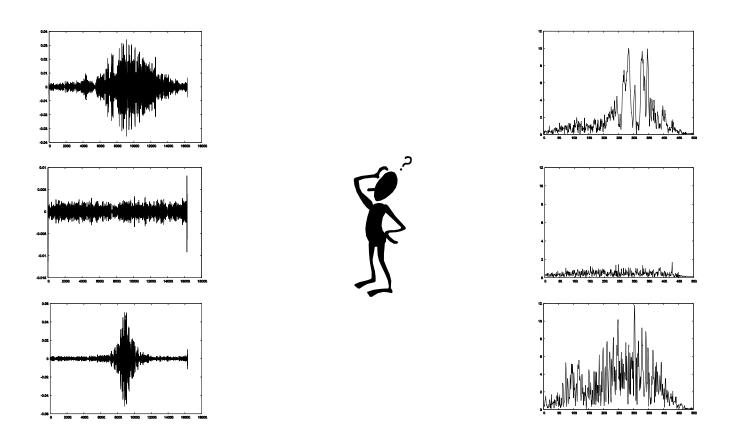


### Too much data ...

- Two examples for vibration and camera sensors
  - Vibration sensor at 2 kHz sampling frequency
  - Camera sensor at variable 1-3 fps
- One vibration sensor and one camera sensor
  - 710 hours of measurement, i.e. ~30 days
  - 5,004,130,000 vibration sensor measurement values
  - 1.7 TB data for vibration and camera sensor
- Three vibration sensors and one camera sensor
  - 6 hours of measurement
  - 128,888,596 vibration sensor measurement values
  - 25,076 camera sensor image files



#### ... and not enough knowledge





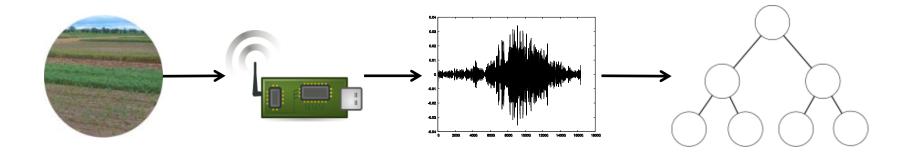
### Challenges

- Data acquisition, processing, storage, and retrieval
  - Heterogeneous communication technology, protocols, data types, etc.
  - Data management and retrieval systems
- Big data may not be *feasible* 
  - "[B]eing able to manage and process [...] those data is going to be a huge challenge" (National Ecological Observatory Network [3])
- Big data may not be *useful* 
  - "[B]eing able [...] to make sense of those data is going to be a huge challenge" [3]
- Data-rich and knowledge-poor environment



### To make sense of sensor data

How to acquire knowledge



How to **represent** knowledge



## Ontology

- Defined as "an explicit specification of a conceptualization" [4]
- A means to formally represent knowledge of a domain
  - Concepts of some area of interest (i.e. domain)
  - Relations that hold among concepts
- Example (e.g. domain of road vehicles)
  - WeightCategory(light)
  - WeightCategory(heavy)
  - LightVehicle ⊑ Vehicle ⊓ ∀hasWeightCategory.{light}
  - HeavyVehicle ⊑ Vehicle ⊓ ∀hasWeightCategory.{heavy}
  - − LightVehicle  $\sqcap$  HeavyVehicle  $\sqsubseteq \bot$
  - VehicleObservation ⊑ Observation ⊓ ∀featureOfInterest.Vehicle

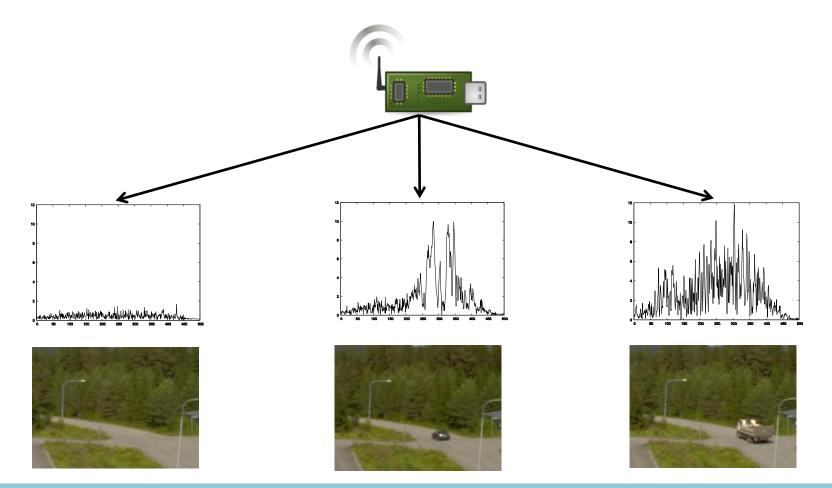


### Monitoring road vehicles

- Example used here
- Aim is detection and classification of vehicles
  - Is a vehicle observed by a sensor (now)?
  - If so, what vehicle type is it?
  - Machine learning (ML) classification
    - ~8 s of measurement used as pattern for classification
    - Supervised learning for pattern classification
- More aims
  - Infer when different sensors have observed the same vehicle
  - Infer vehicle velocity (speed, driving direction, driving side)

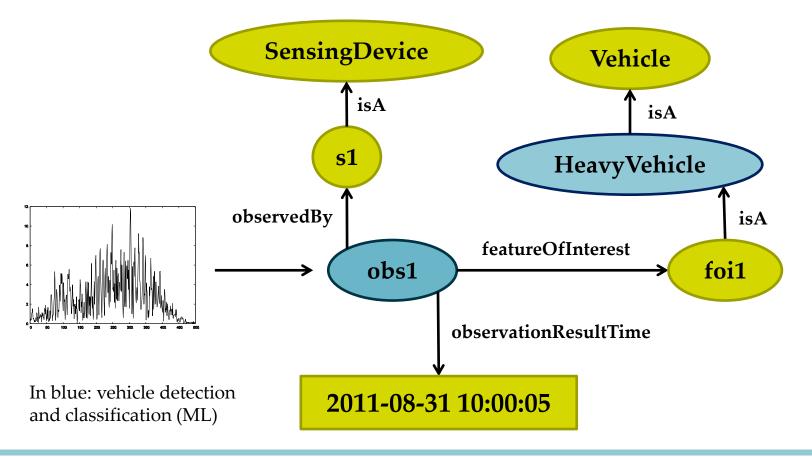


#### **Patterns for classification (ML)**



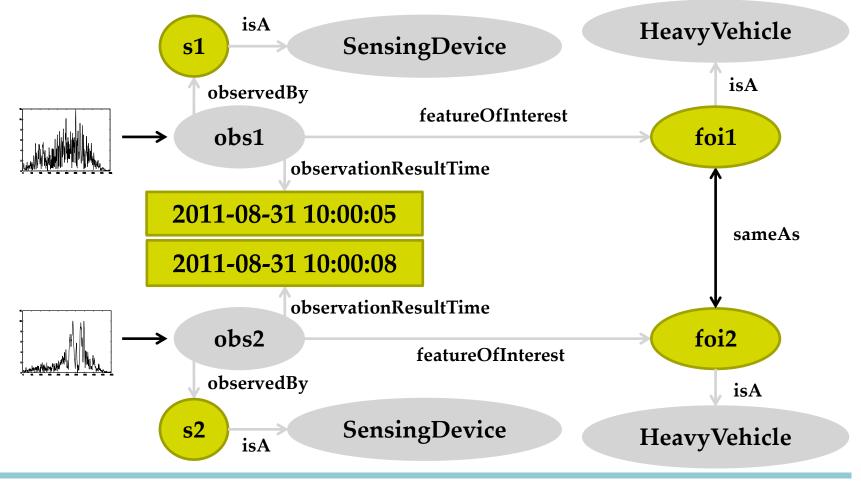


### **Knowledge representation Observation for a vehicle**

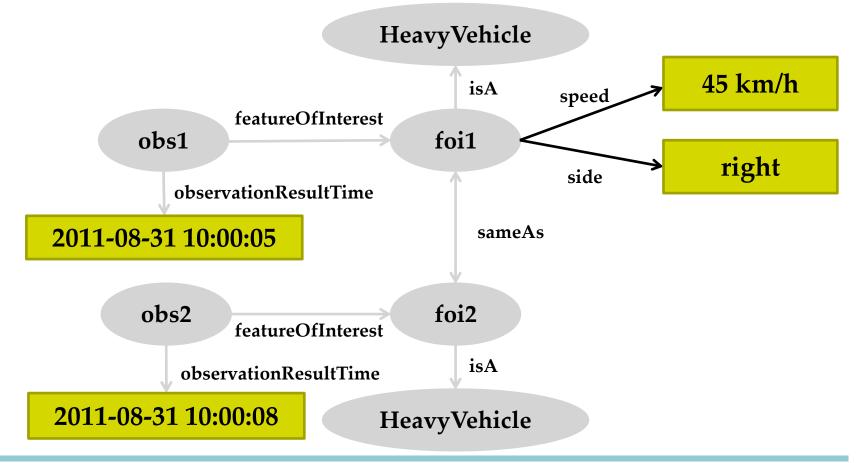




### **Knowledge representation Two observations for same vehicle**

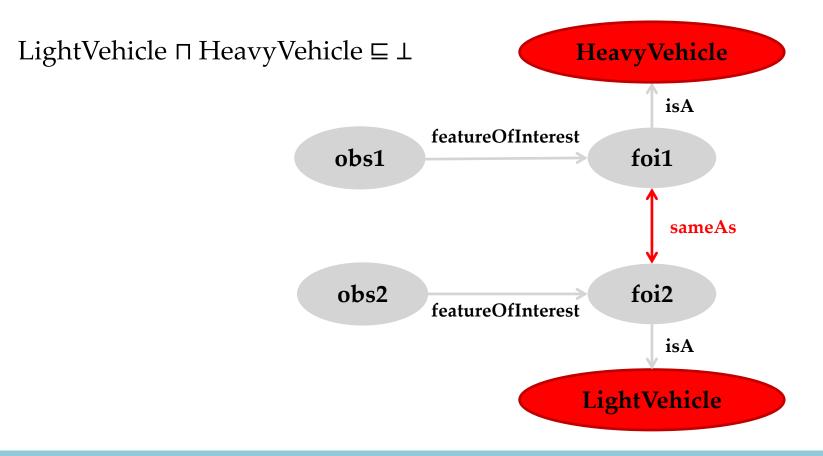


### **Knowledge representation Inference of velocity**





**Knowledge representation Consistency checking** 





### Conclusions

- Sensors and sensor networks can produce a lot of data
  - We are typically not interested in such data
  - We are interested in what those data tell
- We discussed automated workflow for
  - Sensor data acquisition and processing
  - Knowledge acquisition and representation
- Benefits of knowledge representation
  - Abstraction, inference, consistency checking, query, visualization
- Situation awareness? [5]
  - Perception: sensor network perceives status of elements in the environment
  - Comprehension: ontology as "holistic picture of the environment"
  - Projection: ontology reasoning
  - A methodology for situation assessment



### References

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