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Abstractions from Sensor Data with Complex Event Processing and Machine Learning

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Introduction

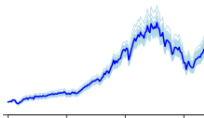
- ▶ Environmental sensor networks (ESN)
 - ▶ Important tool in environmental science
- ▶ Large amounts of heterogeneous data
- ▶ Organize and interpret ESN data
- ▶ Building on ESNs
 - ▶ Environmental data systems
 - ▶ Environmental knowledge systems

Problem

What we have



1.12483456780
2.59901521668
3.93918999451
1.28316206864
8.15483832459
2.15588315924
1.12483456780
2.59901521668
3.93918999451
1.28316206864
8.15483832459
2.15588315924



What we need more



Starting point

- ▶ ESNs do not measure situational knowledge
 - ▶ But spatio-temporal change of physical properties
- ▶ We have data for properties
- ▶ We want situational knowledge
 - ▶ Information for situations
 - ▶ Situations are “structured parts of reality” [1]
 - ▶ Include objects, information for their state
- ▶ Assumed we can get from data to knowledge
 - ▶ Automatically using computational methods
 - ▶ Possibly (expert) supervised

Methods of interest

- ▶ Knowledge representation
 - ▶ Represent data and knowledge
- ▶ Knowledge extraction
 - ▶ Rule-based reasoning
 - ▶ Complex event processing (CEP)
 - ▶ Machine learning (ML)
 - ▶ Physically-based models
- ▶ Data processing
 - ▶ Aggregation, interpolation, filtering, ...

What we did

- ▶ Use CEP and ML to get from data to knowledge
- ▶ In Wavellite
 - ▶ Modelling and software framework
 - ▶ Situation awareness in environmental monitoring
 - ▶ Four layers with components and modules
 - ▶ Core data abstractions
 - ▶ Sensor observation, dataset observation, situation
 - ▶ These are ontological classes
- ▶ Learning modules of particular interest here
 - ▶ Implement program logic to extract knowledge
 - ▶ From dataset observations (input)
 - ▶ Represented as situations (output)

What we did

- ▶ Implementations for CEP with Esper and ML with WEKA
- ▶ CEP and Esper
 - ▶ Provide EPL statements
 - ▶ Executed by CEP engine on dataset observations
 - ▶ Events form situational knowledge
- ▶ ML and WEKA
 - ▶ Provide (trained) classifier
 - ▶ Classify dataset observations
 - ▶ Class labels form situational knowledge

Examples

- ▶ CEP and Esper
 - ▶ Sensor measures wind speed
 - ▶ Data represented as sensor observations
 - ▶ Processed to dataset observations
 - ▶ EPL statement for strong winds (wind speed > threshold)
 - ▶ CEP engine returns events matching EPL statement
 - ▶ Events include situational knowledge for strong winds
- ▶ ML and WEKA
 - ▶ Sensor observations for road pavement vibration
 - ▶ Processed to dataset observations for vibration patterns
 - ▶ Classify patterns to detect and characterize vehicles
 - ▶ Class label is situational knowledge for vehicle type

Take away

- ▶ In applications on ESNs
 - ▶ Problem-specific knowledge extraction
 - ▶ Support range of computational methods
 - ▶ Situation theory / awareness useful
 - ▶ Build knowledge representation into systems

References I

- [1] K. Devlin.
Logic and information.
Cambridge University Press, 1995.

Pictures:

* Environmental monitoring station

<http://ndep.nv.gov/baqp/monitoring.html>

* Database

<http://www.inkwellimages.ie/webdesign/uploads/images/stock/png/computer-database-psd-icon-400x320.png>

* Timeseries

<http://freakonometrics.blog.free.fr/public/perso6/sp500-ok-evol-jack.png>

* Situation

<http://www.relocateaz.com/wp-content/uploads/2014/05/monsoon-driving.jpg>